



Outline

N and P in a bottle

Tritium Example

Propagation of a  
perturbation

# Lab 11

## Finite Difference Methods

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Plan for today:

- Finite Difference Approximation of N and P in a bottle using “Euler Forward” scheme (implicit vs. explicit)
- Finite Difference Approximation of tritium in a pipe using “FTCS” scheme
- Finite Difference Approximation of advection of a perturbation using “Upwind” scheme



Phytoplankton culture,  $P$  [mmol N/m<sup>3</sup>], in a bottle with nutrient,  $N$  [mmol N/m<sup>3</sup>], and you know that uptake occurs according to Michaelis-Menten kinetics; you also know the uptake parameters approximately.

$$\begin{aligned}\frac{dP}{dt} &= \mu_{max} \frac{N}{k_N + N} P - rP \\ \frac{dN}{dt} &= -\mu_{max} \frac{N}{k_N + N} P + rP\end{aligned}$$

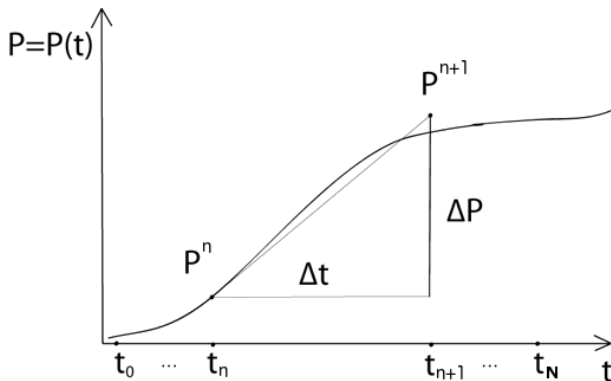
Recipe: replace  $\frac{dP}{dt}$  by  $\frac{\Delta P}{\Delta t}$  and  $\frac{dN}{dt}$  by  $\frac{\Delta N}{\Delta t}$

## Conventions:

We want to solve for discrete time steps,  $t_i$  between  $t_0$  and  $t_{end}$ :

$$t_n = t_0 + n \times \Delta t \quad (n = 0, \dots, N)$$

Refer to  $N, P$  at  $t_i$  as  $N_i, P_i$ .



# "Euler forward"



$$\begin{aligned}\frac{P^{n+1} - P^n}{\Delta t} &= \mu_{max} \frac{N^n}{k_N + N^n} P^n - rP^n \\ \frac{N^{n+1} - N^n}{\Delta t} &= -\mu_{max} \frac{N^n}{k_N + N^n} P^n + rP^n\end{aligned}$$

## "Euler forward"



$$\frac{P^{n+1} - P^n}{\Delta t} = \mu_{max} \frac{N^n}{k_N + N^n} P^n - rP^n$$
$$\frac{N^{n+1} - N^n}{\Delta t} = -\mu_{max} \frac{N^n}{k_N + N^n} P^n + rP^n$$

and rearranging yields:

$$P^{n+1} = P^n + \Delta t \left( \mu_{max} \frac{N^n}{k_N + N^n} P^n - rP^n \right)$$
$$N^{n+1} = N^n + \Delta t \left( -\mu_{max} \frac{N^n}{k_N + N^n} P^n + rP^n \right)$$

## N and P in a bottle



Follow along script NP\_bottle.m.

```
% 1.) set constants
dt      = 0.1;      % time step (in days)
k_N     = 0.75;     % half sat. const. of N (in muM)
mu_max  = 1.2;     % maximum growth rate (in days-1)
r       = 0.1;     % respiration rate (in days-1)
n_max   = 100;     % maximum number of timesteps

% 2.) initialize state variables N and P
% (and time -- only for plotting purposes)
N = zeros(1,n_max);
P = zeros(1,n_max);
t = zeros(1,n_max);
N(1) = 5.0;      % in muM; N at t0
P(1) = 0.1;     % in muM; P at t0
t(1) = 0;       % in days; t0
```



```
% 3.) calculate numerical solution from t1 to t_end
for n = 2:n_max
    t(n) = t(n-1)+dt;
    uptake = mu_max*N(n-1)/(k_N+N(n-1));
    P(n) = P(n-1) + dt*( uptake - r)*P(n-1);
    N(n) = N(n-1) + dt*(-uptake + r)*P(n-1);
end

% 4.) plot solution
hFig = figure(1);
hp = plot(t,N,'r.:',t,P,'g.:');
set(hp,'MarkerSize',16)
set(gca,'FontSize',16)
xlabel('time (day)')
ylabel('concentration of N and P (muM)')
legend('N','P', 'Location', 'best')
```

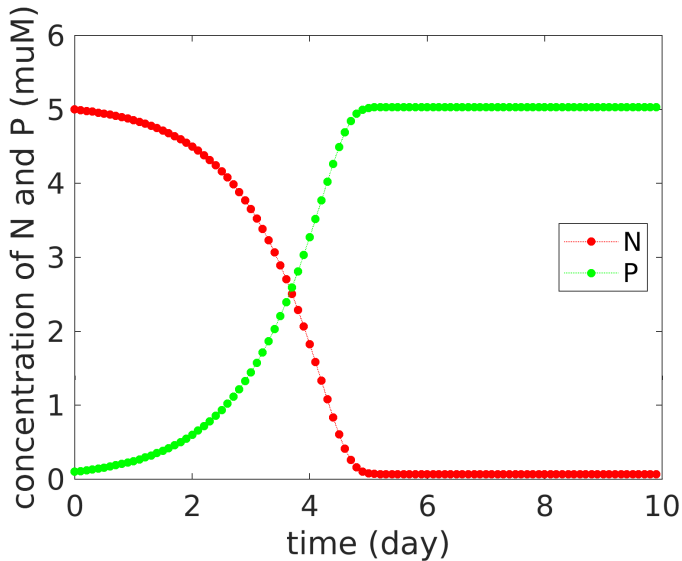




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So far we have used a time step of 0.1 d.

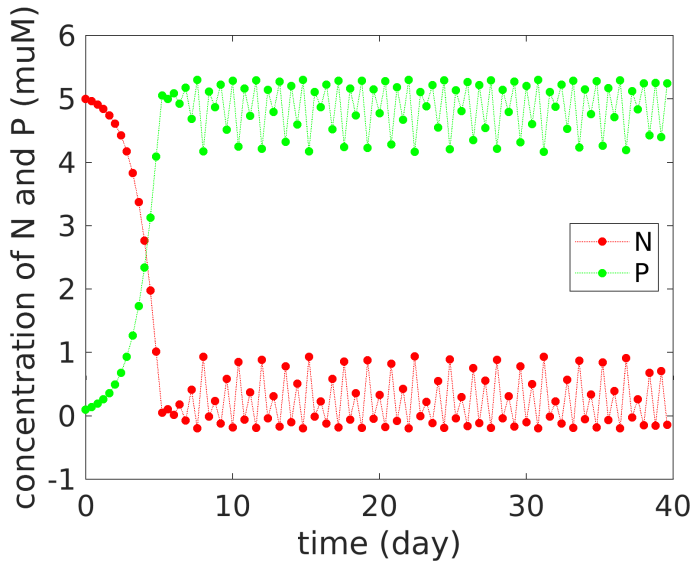
Now increase time step to 0.4 d and see what happens.



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$$P^{n+1} = P^n + \Delta t \left( \mu_{max} \frac{N^n}{k_N + N^n} P^n - rP^n \right)$$
$$N^{n+1} = N^n + \Delta t \left( -\mu_{max} \frac{N^n}{k_N + N^n} P^n + rP^n \right)$$

Note that only concentrations from "previous" time point  $n$  are used to arrive at "next" time point  $(n + 1)$ .

$$C^{n+1} = f(C^n) \quad \text{"explicit scheme"}$$

Think about the implications in terms of "tangent on the curve" or "control volume".



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Wouldn't it be more "accurate" to allow  $C$  to change over the time period  $\Delta t$ ?

$$C^{n+1} = f(C^n, C^{n+1}) \quad \text{"implicit scheme"}$$



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May seem tricky, but is tractable.

Leads to a set of simultaneous equations that need to be solved for each time step (not bad in one dimension, but gets expensive for higher spatial dimensions).

Example for nutrient uptake:

$$\begin{aligned} \frac{dN}{dt} &= -\mu \frac{N}{k + N} P \\ \frac{N^{n+1} - N^n}{\Delta t} &= -\mu \frac{N^{n+1}}{k + N^n} P^n \end{aligned}$$



$$N^{n+1} = \frac{N^n}{1 + \frac{\mu \Delta t P^n}{k + N^n}}$$

A non-negative number is divided by a positive number.  
This scheme is **positive definite**.

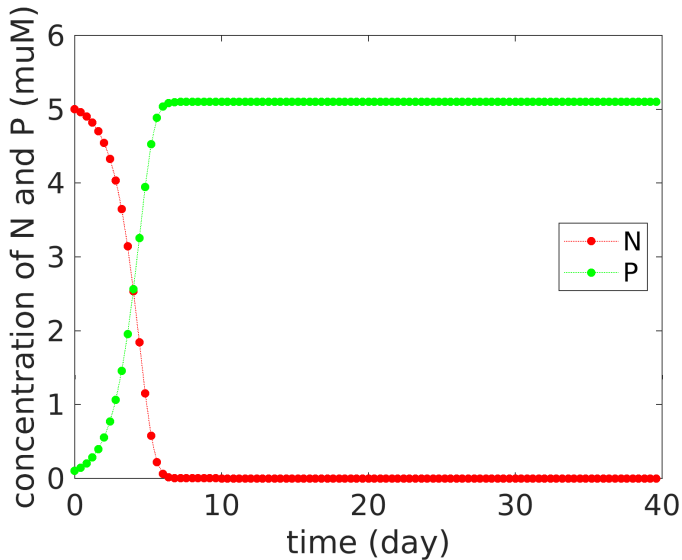
See script `NP_bottle_impl.m`.



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## Key change to make the scheme implicit:

### Explicit:

```
for n = 2:n_max
    t(n) = t(n-1)+dt;
    uptake = mu_max*N(n-1) / (k_N+N(n-1));
    P(n) = P(n-1) + dt*uptake*P(n-1);
    N(n) = N(n-1) - dt*uptake*P(n-1);
end
```



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end
```

### Implicit:

```
for n = 2:n_max
    t(n) = t(n-1)+dt;
    cff = mu_max*dt*P(n-1) / (k_N+N(n-1));
    N(n) = N(n-1) / (1+cff);
    P(n) = P(n-1) + cff*N(n);
end
```

## FTCS example: Tritium in a pipe



- Pipe with water flowing down and mixing.
- Water enters at the surface.
- Imagine pipe as streamline in subtropical gyre.

$$\frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial t} + K \frac{\partial^2 C}{\partial t^2} - \lambda C$$

$$u = 0.01 \text{ ms}^{-1}$$

$$K = 1000 \text{ m}^2\text{s}^{-1}$$

$$\lambda = \frac{1}{18} \text{ yr}^{-1}$$

$$\Delta x = 50,000 \text{ m (assume total length 12,000 km)}$$

$$\Delta t = 200,000 \text{ s (2.5 days)}$$

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In discrete terms:

$$C_i^{n+1} = C_i^n - \frac{u\Delta t}{2\Delta x}(C_{i+1}^n - C_{i-1}^n) + \frac{K\Delta t}{(\Delta x)^2}(C_{i-1}^n + C_{i+1}^n - 2C_i^n) - \Delta t\lambda C_i^n$$

or

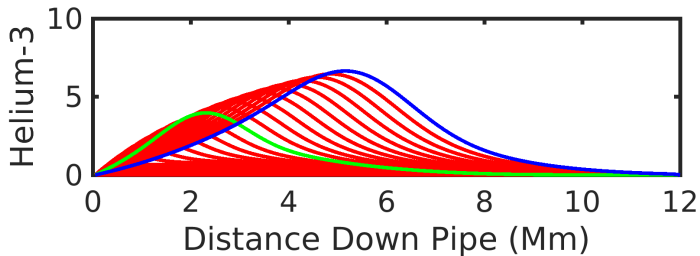
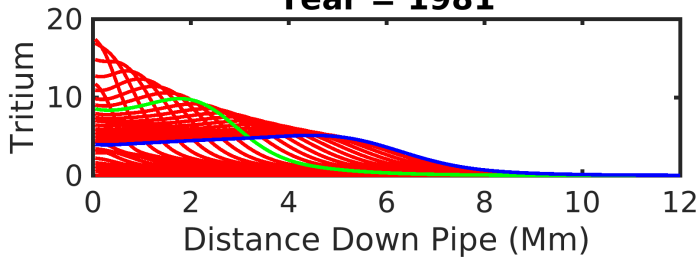
$$C_i^{n+1} = w_- C_{i-1}^n + w_0 C_i^n + w_+ C_{i+1}^n$$

where

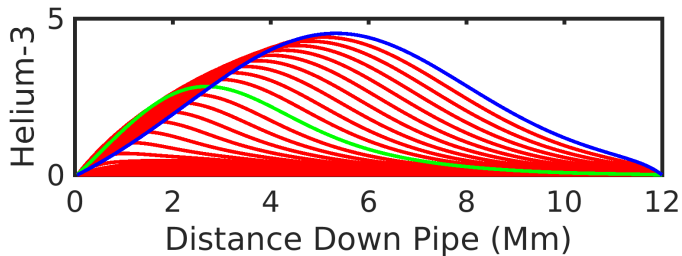
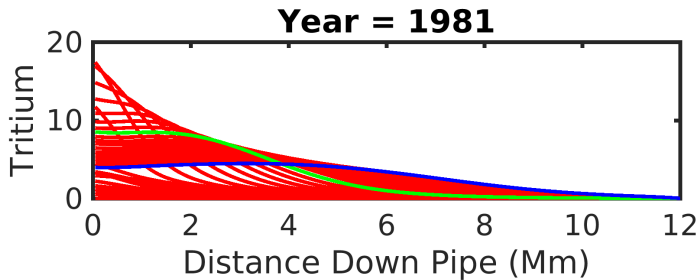
$$\begin{aligned}w_- &= \frac{c}{2} + d \\w_0 &= 1 - \Delta t\lambda - 2d \\w_+ &= -\frac{c}{2} + d\end{aligned}$$

See script `pipe1.m`.

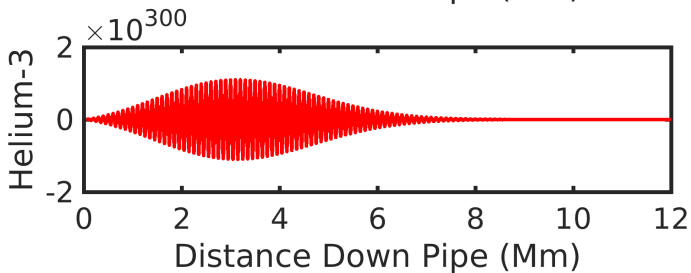
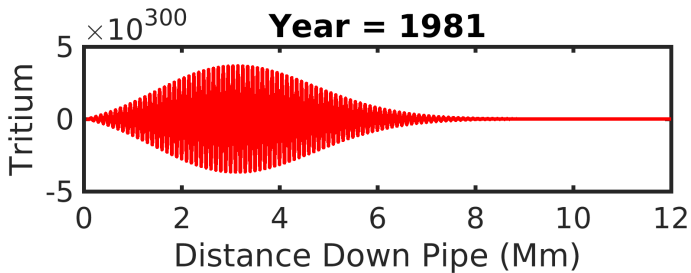
$$K = 1000 \text{ m}^2\text{s}^{-1}$$

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Adding more diffusion:  $K = 5000 \text{ m}^2\text{s}^{-1}$



Even more:  $K = 8000 \text{ m}^2\text{s}^{-1}$  Now unstable!



## “Upwind scheme”

Consider a purely advective, one-dimensional system:

$$\frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial x}$$





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Using FTCS would result in:

$$C_i^{n+1} = C_i^n - \frac{c}{2} (C_{i+1}^n - C_{i-1}^n) \quad \text{with: } c = \frac{u\Delta t}{\Delta x}$$

$C_{i+1}^n$  implies that for  $u > 0$ , downstream information are used to calculate upstream results for next time step.



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$C_{i+1}^n$  implies that for  $u > 0$ , downstream information are used to calculate upstream results for next time step.

Therefore, we choose what information are used depending on the direction of the flow (i.e. the sign of  $u$ ):

$$u > 0: -c (C_i^n - C_{i-1}^n), \quad u < 0: -c (C_{i+1}^n - C_i^n)$$

See script `propagate_step.m`.

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```
tyr = 24*3600*365.25; % seconds per year
dt = 200000;          % time step in seconds
ny = 5;              % number of years
dx = 50000;          % grid size in x-direction
nx = 500;            % # of cells in x-direction
u = 0.02;            % velocity in x-direction
nt = ny*tyr/dt;      % # of time steps
```

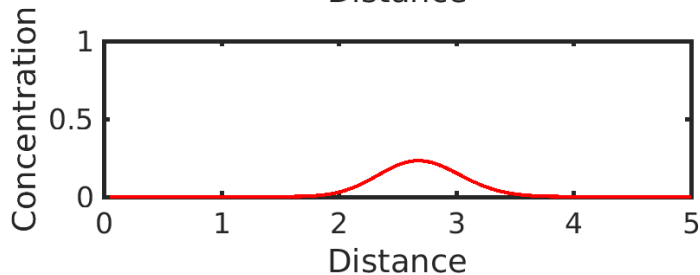
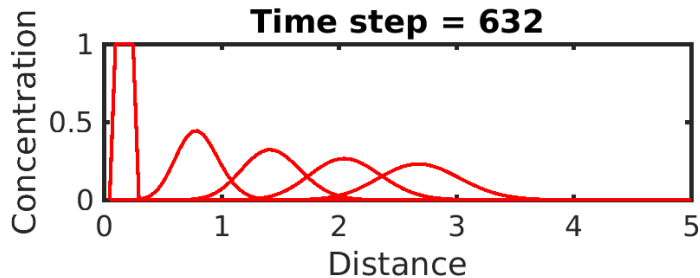


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Due to “numerical diffusion” the equation we actually solved looks like:

$$\frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial x} + K_n \frac{\partial^2 C}{\partial x^2}, \quad \text{with: } K_n = \frac{u \Delta x}{2} (1 - c)$$

If  $c = u \frac{\Delta x}{\Delta t} = 1$ , the numerical diffusion vanishes.

Back to `propagate_step.m`.

Now try:  $dt = dx/u$

# Numerical diffusion

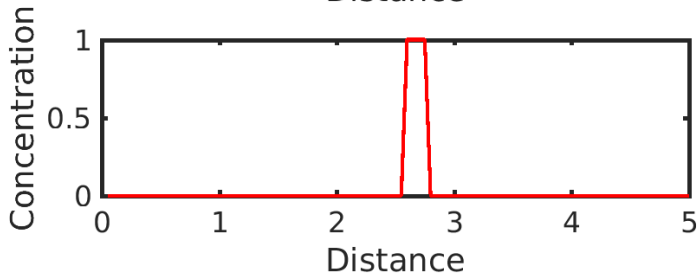
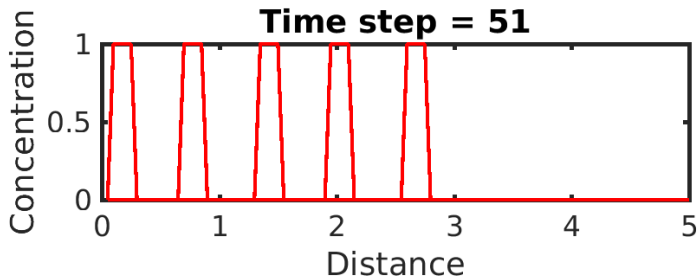


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# Recommendations

- Keep it **simple**.
- **Don't reinvent** the wheel.
- **Know** your tools.
- Carry along **checksums/tests**.
- Test your model with idealized functions or well-known scenarios (**test cases**).
- Compute but recognize the scheme's limitations.

